

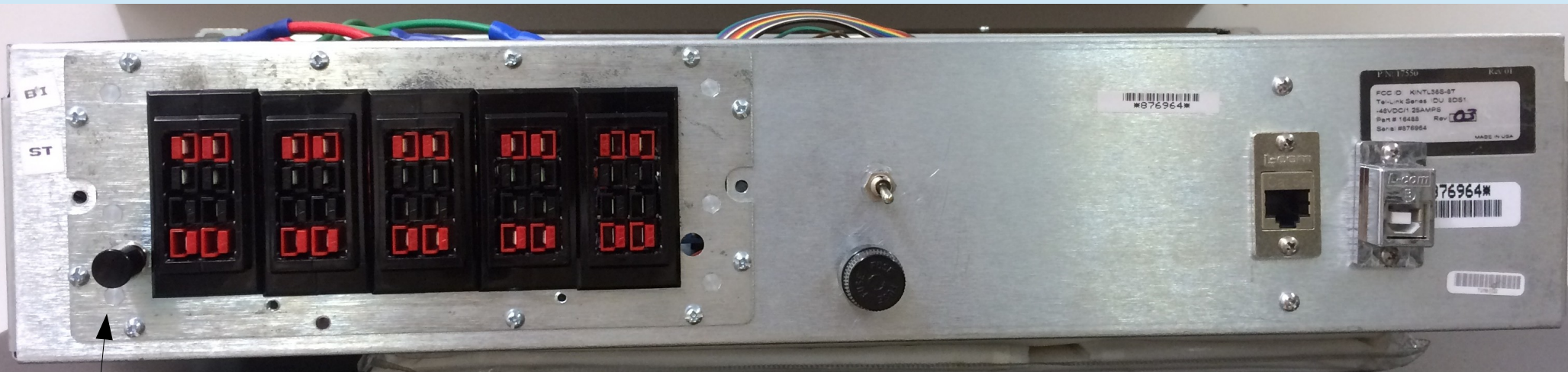
Arduino Ethernet Device Control Example

Arduino Ethernet Device Control Example

- Use Arduino to create a web page, provide on/off control for 16 devices via the Ethernet
 - Can use for power control,
 - transverter or antenna bandswitching,
 - switching mic, receive audio, foot switch, CW key, etc. among IF rigs
 - turning cameras on/off or switching between cameras

Arduino Ethernet Device Control Example

- Originally needed to use MEGA due to memory requirements:
 - Used 4084 bytes of SRAM (dynamic memory)
 - UNO only has 2048 bytes of SRAM
- Subsequent coding changes reduced SRAM to 1598
- Arduino MEGA and ethernet shield from eBay
 - Cost \$13.66 with free shipping



RESET Button



COM Tel-Link

ON-LINE

STATUS & CONTROL


ALARMS

- IDU
- ODU
- CBL
- RMT

AGC GND COMPUTER

A
R
T

IDU0008284



ALARMS I/O

DC INPUT

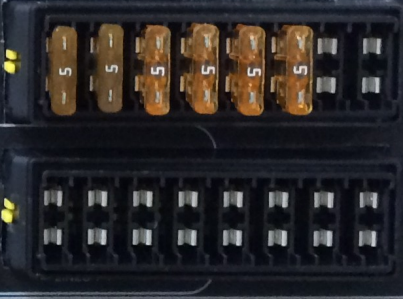
PC

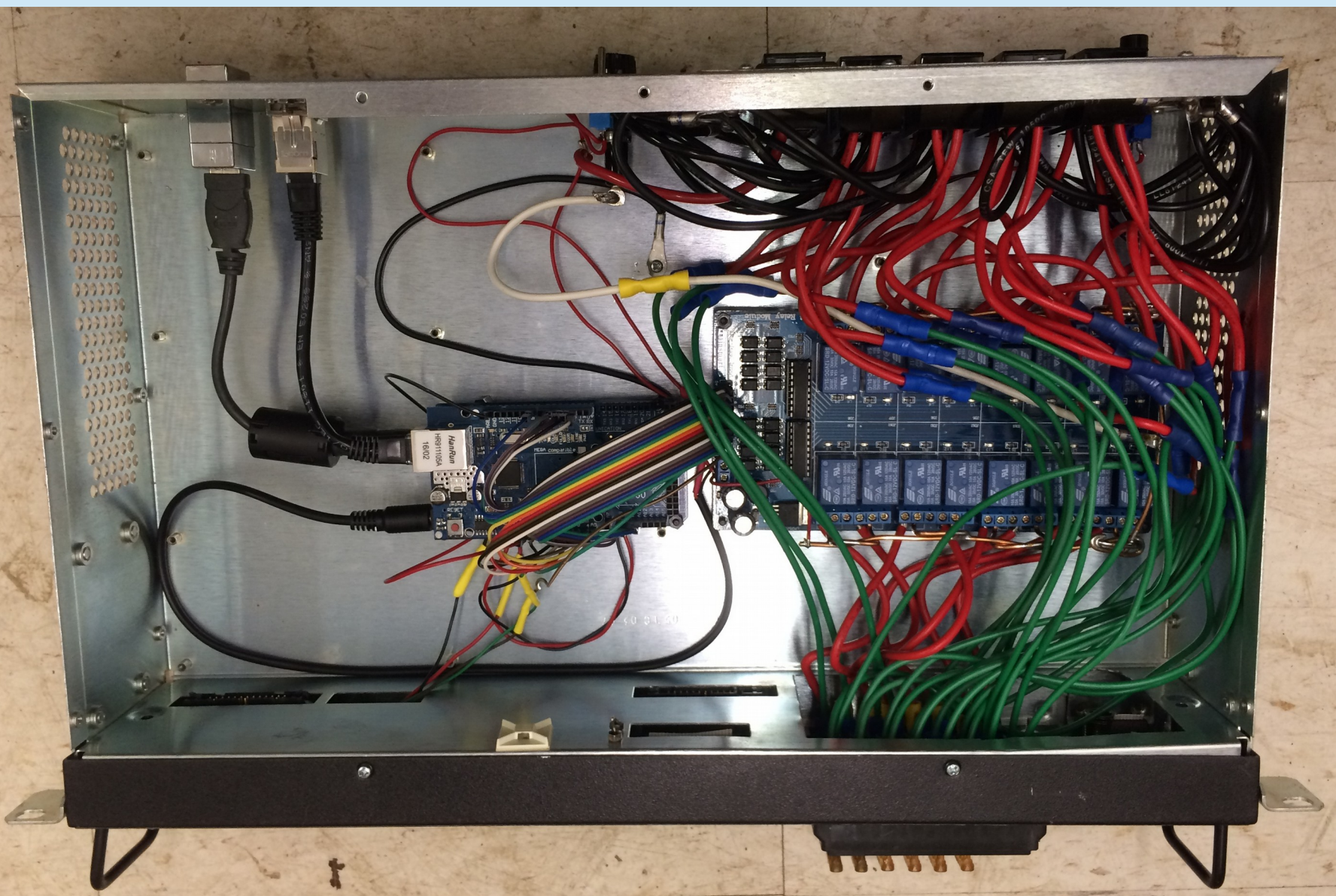
LINK

NMS 1

NMS 2

ODU





W3SZ Ethernet Relay Control

Click On Relay Buttons To Change State

GET STATUS

WATTMETER **SWR METER**

SWR-CAM ON **SWR-CAM OFF**

WATT-CAM ON **WATT-CAM OFF**

TX ANT ON **TX ANT OFF**

VNA ON **VNA OFF**

Relay 6 ON **Relay 6 OFF**

Relay 7 ON **Relay 7 OFF**

Relay 8 ON **Relay 8 OFF**

Relay 9 ON **Relay 9 OFF**

Relay 10 ON **Relay 10 OFF**

Relay 11 ON **Relay 11 OFF**

Relay 12 ON **Relay 12 OFF**

Relay 13 ON **Relay 13 OFF**

Relay 14 ON **Relay 14 OFF**

Relay 15 ON **Relay 15 OFF**

Relay 16 ON **Relay 16 OFF**

Arduino Ethernet Device Control Live Demo

Arduino Ethernet Device Control Example: Arduino Code

1) Include Libraries that are needed

2) Define/initialize constants and variables

3) Setup()

- Define and initialize output pins

- Start ethernet port and serial port

4) Loop()

- Get ethernet data

- Parse ethernet data

- Switch relays on or off

5) Call procedure “sendReply” to:

- Send relay status back to client and re-write web page at client

- (Web page uses HTML buttons to send commands to Arduino to control relays and read relay status)

Arduino Ethernet Device Control Example: Arduino Code

- For relay control uses GPIO pins 2-6, 8, A0-A5, A8-A11
- Depending on characteristics of relay board, may need to use reverse logic for relay control
- For this example we will NOT use reverse logic

Include Libraries

```
8  
9 #include <Ethernet.h> //for ethernet port  
10 #include <string.h> // for string handling  
11
```

Define Variables & Constants

```
12 String commandInputString = "";
13 String serIn;
14 String serOut1a;
15 String serOut2a;
16 String serOut3a;
17 String serOut4a;
18 String serOut1b;
19 String serOut2b;
20 String serOut3b;
21 String serOut4b;
22 String serOut5a;
23 String serOut6a;
24 String serOut7a;
25 String serOut8a;
26 String serOut9a;
27 String serOut5b;
28 String serOut6b;
29 String serOut7b;
30 String serOut8b;
31 String serOut9b;
```

```
32 String serOut10a;
33 String serOut11a;
34 String serOut12a;
35 String serOut13a;
36 String serOut14a;
37 String serOut15a;
38 String serOut16a;
39 String serOut10b;
40 String serOut11b;
41 String serOut12b;
42 String serOut13b;
43 String serOut14b;
44 String serOut15b;
45 String serOut16b;
46
47 const int ON = 1;
48 const int OFF = 0;
```

Ethernet.h

- Library to work with Ethernet Shield, Ethernet Shield 2, and Leonardo Ethernet. Contains the classes:

Ethernet: members `begin()`, `localIP()`, `maintain()`

IPAddress: member `IPAddress()`

Server: members `Server`, `EthernetServer()`, `begin()`, `available()`, `write()`, `print()`, `println()`

Client: members `Client`, `EthernetClient()`, `if(EthernetClient)`, `connected()`, `connect()`, `write()`, `print()`, `println()`, `available()`, `read()`, `flush()`, `stop()`

EthernetUdp members `begin()`, `read()`, `write()`, `beginPacket()`, `endPacket()`, `parsePacket()`, `available()`, `stop()`, `remoteIP()`, `remotePort()`

Define Variables & Constants

`IPAddress(address)`: a comma delimited list representing the address (4 bytes, ex. 192, 168, 1, 1). Returns nothing.

`EthernetServer(port)`: Create a server that listens for incoming connections on the specified port. Returns nothing.

```
50 // Enter MAC address and IP address for Arduino.
51 // The IP address is dependent on your local network:
52 byte mac[] = { 0x90, 0xAA, 0xBB, 0xCC, 0xDA, 0x02 };
53 IPAddress ip(192, 168, 10, 176); //<< ENTER YOUR IP ADDRESS HERE <<
54
55 // Initialize the Ethernet server library
56 // We'll use port 80 for HTTP):
57 EthernetServer server(80);
58 EthernetClient client;
59
60 const int PinR1 = 2; //number of Relay 1 pin
61 const int PinR2 = 3; //number of Relay 2 pin
62 const int PinR3 = 4; //number of Relay 3 pin
63 const int PinR4 = 5; //number of Relay 4 pin
64 const int PinR5 = 6; //number of Relay 5 pin
65 const int PinR6 = 8; //number of Relay 6 pin
66 const int PinR7 = A5; //number of Relay 7 pin
67 const int PinR8 = A4; //number of Relay 8 pin
68 const int PinR9 = A3; //number of Relay 9 pin
69 const int PinR10 = A2; //number of Relay 10 pin
70 const int PinR11 = A1; //number of Relay 11 pin
71 const int PinR12 = A0; //number of Relay 12 pin
72 const int PinR13 = A8; //number of Relay 13 pin
73 const int PinR14 = A9; //number of Relay 14 pin
74 const int PinR15 = A10; //number of Relay 15 pin
75 const int PinR16 = A11; //number of Relay 16 pin
```

`EthernetClient`: Create a client that can connect to a server. Returns nothing.

Setup: Initialize GPIO Pins

```
78 void setup()
79 {
80     // initialize GPIO pins as output pins
81     pinMode(PinR1, OUTPUT);
82     pinMode(PinR2, OUTPUT);
83     pinMode(PinR3, OUTPUT);
84     pinMode(PinR4, OUTPUT);
85     pinMode(PinR5, OUTPUT);
86     pinMode(PinR6, OUTPUT);
87     pinMode(PinR7, OUTPUT);
88     pinMode(PinR8, OUTPUT);
89     pinMode(PinR9, OUTPUT);
90     pinMode(PinR10, OUTPUT);
91     pinMode(PinR11, OUTPUT);
92     pinMode(PinR12, OUTPUT);
93     pinMode(PinR13, OUTPUT);
94     pinMode(PinR14, OUTPUT);
95     pinMode(PinR15, OUTPUT);
96     pinMode(PinR16, OUTPUT);
```

```
98     //initialize all GPIO pin values to OFF
99     digitalWrite(PinR1, OFF);
100    digitalWrite(PinR2, OFF);
101    digitalWrite(PinR3, OFF);
102    digitalWrite(PinR4, OFF);
103    digitalWrite(PinR5, OFF);
104    digitalWrite(PinR6, OFF);
105    digitalWrite(PinR7, OFF);
106    digitalWrite(PinR8, OFF);
107    digitalWrite(PinR9, OFF);
108    digitalWrite(PinR10, OFF);
109    digitalWrite(PinR11, OFF);
110    digitalWrite(PinR12, OFF);
111    digitalWrite(PinR13, OFF);
112    digitalWrite(PinR14, OFF);
113    digitalWrite(PinR15, OFF);
114    digitalWrite(PinR16, OFF);
```

Setup: Start Ethernet Port

```
116 // start the Ethernet connection and the server and the serial port:
117 Ethernet.begin(mac, ip);
118 server.begin();
119 Serial.begin(9600);
120 Serial.println("Arduino Ethernet Device Switch");
121 Serial.println("by W3SZ");
122 Serial.println("Starting Server");
123 Serial.println (Ethernet.localIP());
124
125
126 }
```

`Ethernet.begin(mac, ip):`
Initializes the ethernet library and network settings to mac address mac and IPAddress ip. mac is array of 6 bytes. ip is array of 4 bytes. Returns nothing.

`EthernetServer.begin():`
Start server listening for clients

Arduino Ethernet Device Control Example:

Loop to Get Ethernet Data, Parse It, Switch Relays, Send Status Back to HTML Client and Refresh Web Page

```
470 void loop()
471 {
472   // listen for incoming client
473   client = server.available();
474   if (client) {
475     while (client.connected()) {
476       char c = client.read();
477       commandInputString += c; //append latest character received to string
478       if (c == '\n')
479       {
480         //Checks for the URL string beginning with '~' and ending with '$'
481         int stringStart = commandInputString.indexOf('~');
482         int stringEnd = commandInputString.indexOf('$');
483         String commandOut = commandInputString.substring(1 + stringStart, stringEnd);
484         Serial.print("Command is: ");
485         Serial.println(commandOut);
486         Serial.println(" ");
```

EthernetServer.available(): Gets a Client that is connected to the server and has data available for reading. Returns a Client object, or false if no client has data available

EthernetClient.connected(): Returns TRUE if client connected or if client is closed but there is still unread data; otherwise false

EthernetClient.read(): Reads the next byte received from the server the client is connected to. Returns the next byte, or -1 if none available

Arduino String class

- Members include:

charAt

compareTo

concat

c_str

endsWith

equals

equalsIgnoreCase

getBytes

indexOf

lastIndexOf

length

remove

replace

reserve

setCharAt

startsWith

substring

toCharArray

toInt

toFloat

toLowerCase

toUpperCase

trim

Arduino Ethernet Device Control Example:

Loop to Get Ethernet Data, Parse It, Switch Relays, Send Status Back to HTML Client and Refresh Web Page

```
470 void loop()
471 {
472   // listen for incoming client
473   client = server.available();
474   if (client) {
475     while (client.connected()) {
476       char c = client.read();
477       commandInputString += c; //append latest character received to string
478       if (c == '\n')
479       {
480         //Checks for the URL string beginning with '~' and ending with '$'
481         int stringStart = commandInputString.indexOf('~');
482         int stringEnd = commandInputString.indexOf('$');
483         String commandOut = commandInputString.substring(1 + stringStart, stringEnd);
484         Serial.print("Command is: ");
485         Serial.println(commandOut);
486         Serial.println(" ");

```

String.indexOf(val) Locates a character or String val within another String. Returns the index (position) of val within the String, or -1 if not found. Indexing starts with 0.

String.substring(val1, val2) Gets a substring of a String, starting with val1 and ending before val2. The starting index val1 is inclusive (the corresponding character is included in the substring), but the optional ending index val2 is exclusive. Returns the substring.

Where did this arcane client/server stuff come from?

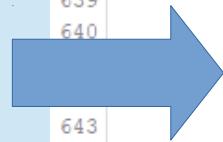
- <http://www.instructables.com/id/Arduino-Ethernet-Shield-Tutorial/> has an example that turns LED on and off via the ethernet...a perfect beginning for this project!
- Original Arduino code is here:
http://w3sz.com/EthernetLED_Switch.ino
- Remember, if you start by stealing someone else's code, you will progress much more quickly

Switch the relays

```
488     if (commandOut == "1") {
489         digitalWrite(PinR1, ON);
490         sendReply();
491     }
492     else if (commandOut == "100") {
493         digitalWrite(PinR1, OFF);
494         sendReply();
495     }
496
497     else if (commandOut == "2") {
498         digitalWrite(PinR2, ON);
499         sendReply();
500     }
501     else if (commandOut == "200") {
502         digitalWrite(PinR2, OFF);
503         sendReply();
504     }
505
506     else if (commandOut == "3") {
507         digitalWrite(PinR3, ON);
508         sendReply();
509     }
510     else if (commandOut == "300") {
511         digitalWrite(PinR3, OFF);
512         sendReply();
513     }
```

```
515     else if (commandOut == "4") {
516         digitalWrite(PinR4, ON);
517         sendReply();
518     }
519     else if (commandOut == "400") {
520         digitalWrite(PinR4, OFF);
521         sendReply();
522     }
523
524     else if (commandOut == "5") {
525         digitalWrite(PinR5, ON);
526         sendReply();
527     }
528     else if (commandOut == "500") {
529         digitalWrite(PinR5, OFF);
530         sendReply();
531     }
532
533     else if (commandOut == "6") {
534         digitalWrite(PinR6, ON);
535         sendReply();
536     }
537     else if (commandOut == "600") {
538         digitalWrite(PinR6, OFF);
539         sendReply();
540     }
```

What about
SendReply?



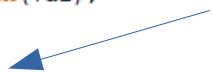
```
615     else if (commandOut == "15") {
616         digitalWrite(PinR15, ON);
617         sendReply();
618     }
619     else if (commandOut == "1500") {
620         digitalWrite(PinR15, OFF);
621         sendReply();
622     }
623
624     else if (commandOut == "16") {
625         digitalWrite(PinR16, ON);
626         sendReply();
627     }
628     else if (commandOut == "1600") {
629         digitalWrite(PinR16, OFF);
630         sendReply();
631     }
632
633     else if (commandOut == "STATUS") {
634         sendReply();
635     }
636     else
637     {
638         String HTMLString = "Command Not Recognized: ";
639         Serial.println(commandOut);
640         Serial.println(HTMLString);
641         sendReply();
642     }
643
644     commandInputString = "";
645     commandOut = "";
646     c=' ';
647
648     }
649 }
650 }
651 }
```

SendReply() Function

- This routine reads the GPIO pin values and reports them both through the serial port and to the HTML client
- It also creates the web page for the HTML client, including the HTML buttons on the web page and defines what is sent to the Arduino when each button is clicked on the web page

```
130 void sendReply()
131 {
132
133     //read all output pin values
134     bool val = digitalRead(PinR1);
135     Serial.println(val);
136     if (val == ON)
137     {
138         serOut1a = F("<input type=button value = 'WATTMETER' onmousedown=location.href='/~1$' style = 'background-color:lime'>");
139         serOut1b = F("<input type=button value = 'SWR METER' onmousedown=location.href='/~100$' style = 'background-color:silver'>");
140     }
141     else if (val == OFF)
142     {
143         serOut1a = F("<input type=button value = 'WATTMETER' onmousedown=location.href='/~1$' style = 'background-color:silver'>");
144         serOut1b = F("<input type=button value = 'SWR METER' onmousedown=location.href='/~100$' style = 'background-color:lime'>");
145     }
146
147     val = digitalRead(PinR2);
148     Serial.println(val);
149     if (val == ON)
150     {
151         serOut2a = F("<input type=button value = 'SWR-CAM ON' onmousedown=location.href='/~2$' style = 'background-color:lime'>");
152         serOut2b = F("<input type=button value = 'SWR-CAM OFF' onmousedown=location.href='/~200$' style = 'background-color:silver'>");
153     }
154     else if (val == OFF)
155     {
156         serOut2a = F("<input type=button value = 'SWR-CAM ON' onmousedown=location.href='/~2$' style = 'background-color:silver'>");
157         serOut2b = F("<input type=button value = 'SWR-CAM OFF' onmousedown=location.href='/~200$' style = 'background-color:lime'>");
158     }
159 }
```

F macro tells the program to store the string in Flash memory rather than SRAM



```
160     val = digitalRead(PinR3);
161     Serial.println(val);
162     if(val == ON)
163     {
164         serOut3a = F("<input type=button value = 'WATT-CAM ON' style = 'background-color:lime' onmousedown=location.href='/~3$'>");
165         serOut3b = F("<input type=button value = 'WATT-CAM OFF' style = 'background-color:silver' onmousedown=location.href='/~300$'>");
166     }
167     else if (val == OFF)
168     {
169         serOut3a = F("<input type=button value = 'WATT-CAM ON' onmousedown=location.href='/~3$' style = 'background-color:silver'>");
170         serOut3b = F("<input type=button value = 'WATT-CAM OFF' onmousedown=location.href='/~300$' style = 'background-color:lime'>");
171     }
172
173     val = digitalRead(PinR4);
174     Serial.println(val);
175     if(val == ON)
176     {
177         serOut4a = F("<input type=button value = 'TX ANT ON' onmousedown=location.href='/~4$' style = 'background-color:lime'>");
178         serOut4b = F("<input type=button value = 'TX ANT OFF' onmousedown=location.href='/~400$' style = 'background-color:silver'>");
179     }
180     else if (val == OFF)
181     {
182         serOut4a = F("<input type=button value = 'TX ANT ON' onmousedown=location.href='/~4$' style = 'background-color:silver'>");
183         serOut4b = F("<input type=button value = 'TX ANT OFF' onmousedown=location.href='/~400$' style = 'background-color:lime'>");
184     }
```



```
316     val = digitalRead(PinR15);
317     Serial.println(val);
318     if(val == ON)
319     {
320         serOut15a = F("<input type=button value = 'Relay 15 ON' onmousedown=location.href='/~15$' style = 'background-color:lime'>");
321         serOut15b = F("<input type=button value = 'Relay 15 OFF' onmousedown=location.href='/~1500$' style = 'background-color:silver'>");
322     }
323     else if (val == OFF)
324     {
325         serOut15a = F("<input type=button value = 'Relay 15 ON' onmousedown=location.href='/~15$' style = 'background-color:silver'>");
326         serOut15b = F("<input type=button value = 'Relay 15 OFF' onmousedown=location.href='/~1500$' style = 'background-color:lime'>");
327     }
328
329     val = digitalRead(PinR16);
330     Serial.println(val);
331     if(val == ON)
332     {
333         serOut16a = F("<input type=button value = 'Relay 16 ON' onmousedown=location.href='/~16$' style = 'background-color:lime'>");
334         serOut16b = F("<input type=button value = 'Relay 16 OFF' onmousedown=location.href='/~1600$' style = 'background-color:silver'>");
335     }
336     else if (val == OFF)
337     {
338         serOut16a = F("<input type=button value = 'Relay 16 ON' onmousedown=location.href='/~16$' style = 'background-color:silver'>");
339         serOut16b = F("<input type=button value = 'Relay 16 OFF' onmousedown=location.href='/~1600$' style = 'background-color:lime'>");
340     }
```

W3SZ Ethernet Relay Control

Click On Relay Buttons To Change State

GET STATUS

```
342     client.println("HTTP/1.1 200 OK");
343     client.println("Content-Type: text/html");
344     client.println();
345     client.println("<!DOCTYPE HTML>");
346     client.println("<html>");
347     client.println("<HEAD>");
348     client.println("<TITLE>W3SZ Ethernet Relay Switch</TITLE>");
349     client.println("</HEAD>");
350     client.println("<body>");
351     client.println("<br />");
352     client.println("<H1>W3SZ Ethernet Relay Control</H1>");
353     client.println("<H2>Click On Relay Buttons To Change State</H2>");
354     client.println("<br />");
355     client.println("<input type=button value = 'GET STATUS' onmousedown=location.href='/~STATUS$'>");
356     client.println("<br />");
357     client.println("<br />");
358     client.println("<br />");
359     client.println("<style>");
```

EthernetClient.println(data): Prints data, followed by a carriage return ('r') and newline ('n'), to the server a client is connected to. Returns number of bytes written. data can be of type char, byte, int, long, or string.

WATTMETER

SWR METER

SWR-CAM ON

SWR-CAM OFF

WATT-CAM ON

WATT-CAM OFF

TX ANT ON

TX ANT OFF

```
367     client.println("table {");
368     client.println("width: 100%;");
369     client.println("}");
370     client.println("</style>");
371     client.println("<table>");
372     client.println("<tr style='border-top:2px solid #f00; border-bottom:2px solid #f00; border-left:2px solid #f00; border-right:2px solid #f00;'>");
373     client.println("<td>");
374     client.println(serOut1a);
375     client.println(serOut1b);
376     client.println("</td>");
377     client.println("<td>");
378     client.println(serOut2a);
379     client.println(serOut2b);
380     client.println("</td>");
381     client.println("<td>");
382     client.println(serOut3a);
383     client.println(serOut3b);
384     client.println("</td>");
385     client.println("<td>");
386     client.println(serOut4a);
387     client.println(serOut4b);
388     client.println("</td>");
389     client.println("</tr>");
```

VNA ON VNA OFF

Relay 6 ON Relay 6 OFF

Relay 7 ON Relay 7 OFF

Relay 8 ON Relay 8 OFF

```
391     client.println("<tr style='border-bottom:2px solid #f00; border-left:2px solid #f00; border-right:2px solid #f00;'>");
392     client.println("<td>");
393     client.println(serOut5a);
394     client.println(serOut5b);
395     client.println("</td>");
396     client.println("<td>");
397     client.println(serOut6a);
398     client.println(serOut6b);
399     client.println("</td>");
400     client.println("<td>");
401     client.println(serOut7a);
402     client.println(serOut7b);
403     client.println("</td>");
404     client.println("<td>");
405     client.println(serOut8a);
406     client.println(serOut8b);
407     client.println("</td>");
408     client.println("</tr>");
```

Relay 9 ON

Relay 9 OFF

Relay 10 ON

Relay 10 OFF

Relay 11 ON

Relay 11 OFF

Relay 12 ON

Relay 12 OFF

```
411     client.println("<tr style='border-bottom:2px solid #f00; border-left:2px solid #f00; border-right:2px solid #f00;')>
412     client.println("<td>");
413     client.println(serOut9a);
414     client.println(serOut9b);
415     client.println("</td>");
416     client.println("<td>");
417     client.println(serOut10a);
418     client.println(serOut10b);
419     client.println("</td>");
420     client.println("<td>");
421     client.println(serOut11a);
422     client.println(serOut11b);
423     client.println("</td>");
424     client.println("<td>");
425     client.println(serOut12a);
426     client.println(serOut12b);
427     client.println("</td>");
428     client.println("</tr>");
```

```
431     client.println("<tr style='border-bottom:2px solid #f00; border-left:2px solid #f00; border-right:2px solid #f00;'>");
432     client.println("<td>");
433     client.println(serOut13a);
434     client.println(serOut13b);
435     client.println("</td>");
436     client.println("<td>");
437     client.println(serOut14a);
438     client.println(serOut14b);
439     client.println("</td>");
440     client.println("<td>");
441     client.println(serOut15a);
442     client.println(serOut15b);
443     client.println("</td>");
444     client.println("<td>");
445     client.println(serOut16a);
446     client.println(serOut16b);
447     client.println("</td>");
448     client.println("</tr>");
449
450     client.println("</table>");
451
452
453     client.println("</body>");
454     client.println("</html>");
455     // pause to give the browser time to receive the data
456     delay(5);
457     // close the connection:
458     client.stop();
459
460
461 }
```

EthernetClient.stop(): Disconnect from the server. Returns nothing.

Arduino Ethernet Device Control Example: Arduino Code

1) Included Libraries that are needed

2) Defined/initialized constants and variables

3) Setup()

- Defined and initialized output pins

- Started ethernet port and serial port

4) Loop()

- Got ethernet data

- Parsed ethernet data

- Switched relays on or off

5) Called procedure “sendReply” to:

- Send relay status back to client and re-write web page at client

- (Web page used HTML buttons to send commands to Arduino to control relays and read relay status)

THERE'S BEEN A LOT OF CONFUSION OVER 1024 vs 1000,
KBYTE vs KBIT, AND THE CAPITALIZATION FOR EACH.

HERE, AT LAST, IS A SINGLE, DEFINITIVE STANDARD:

SYMBOL	NAME	SIZE	NOTES
kB	KILOBYTE	1024 BYTES or 1000 BYTES	1000 BYTES DURING LEAP YEARS, 1024 OTHERWISE
KB	KELLY-BOOTLE STANDARD UNIT	1012 BYTES	COMPROMISE BETWEEN 1000 AND 1024 BYTES
KiB	IMAGINARY KILOBYTE	$1024\sqrt{2}$ BYTES	USED IN QUANTUM COMPUTING
kb	INTEL KILOBYTE	1023.937528 BYTES	CALCULATED ON PENTIUM FPU.
Kb	DRIVEMAKER'S KILOBYTE	CURRENTLY 908 BYTES	SHRINKS BY 4 BYTES EACH YEAR FOR MARKETING REASONS
KBa	BAKER'S KILOBYTE	1152 BYTES	9 BITS TO THE BYTE SINCE YOU'RE SUCH A GOOD CUSTOMER

I would take 'kibibyte' more seriously if it didn't sound
so much like 'Kibbles N Bits'.