Arduino N1MM Transverter Bandswitch

Arduino N1MM Transverter Bandswitch

- Switch transverter band when band changed in N1MM
 - Separate relay for each band, using Sainsmart Relay Board
- Cover 50 MHz thru 76 GHz
- Use USB serial port for communications between N1MM and the Arduino
 - Use OTRSP (Open Two Radio Switching Protocol)
 - Developed by Paul Young, K1XM

Arduino N1MM Transverter Bandswitch

- 50 MHz-76 GHz \rightarrow 13 bands \rightarrow 13 GPIO pins
- Uses 19% (6366 of 32256 available bytes for Uno) of program storage space <Flash>)
- Uses 24% (511 of 2048 available bytes for Uno) of SRAM (static random access memory), where variables are placed
- UNO has sufficient GPIO pins and memory

SainSmart 16 Channel 12V Relay Module



OTRSP

- For this project, need only one-way communication from N1MM to Arduino
- Need only to send N1MM-Radio-Number (n) and Band (bb)
- In OTRSP-speak, this is sent as "AUXnbb"
 - n is either "1" or "2" and bb is 00 12
 - bb is defined via N1MM Configure page
 - e.g for Radio 1 and 222 MHz, "AUX102" will be sent by N1MM

Port None COM11 COM35 COM2 None None LPT1 LPT2 LPT3	Function	n Keys Radio TS-200 None None None None	Digital Mode	Digi	er Winkey	Mode Control Details Set Set Set Set Set Set Set Set Set Set	Antennas	Score Reportin O SO1V =Always On,RTS =Always Off,RTS	g Broadcast O SO2V =Always Off,T =Always Off,T	Data SO2R x=Both Tx=Both
			ок		Cancel			Help		

M Confi	gurer						\times	
Hardware	Function Keys	s Digital Modes	Other W	inkey Mode Control	Antennas Score Rep	orting Broadcast Data		
Port None	Rad	io	Digi CW/C	Other Details	⊖ so1v	○ so2v	2R	
None	→ TS-2	~ 000		Set		M Com2	×	(
COM11	V None	· ·		Set	DTR=Always On	kand -		
COM35	V None	• •		Set				
None	V None	· · ·		Set	DTR=Always Off	DTR (pin 4) RTS (p	in 7) Radio Nr	
None	None			Set		Always Off 🗸 Alway	s Off 🗸 🛛 Both 🗸	
None				Set			Left Window	
None LPT1 LPT2 LPT3	Non	3		Set Set Set		Allow ext interrupts WinKey DVK Two Radio Protocol Foo OTRSP V Nor	otSwitch (pin 6) ne v	
		ОК	c	Cancel	Help	Help	OK Cancel	

Code	Antenna	Bands (1.8,	Rotor Description	Offset	Bidirectional	
	50	50				
	144	144				
	222	222				
	432	432				
	902	902				
	1296	1296				
	2304	2304				
	3456	3456				
	5760	5760				
	10368	10368				
0	24192	24192				
1	47000	47000				
2	76000	76000				
3						
4						
5						
14 15] Start	N1MM Rotor Progr	ram 🔲 Display Rot	ors Used By This Station	Display Rotors	Responding From Network	

Demo of Arduino N1MM Transverter Bandswitch

Programming Steps - General

1) Include libraries containing classes with external functions (Optional)

2) Define variables and constants (Optional)

3) Setup ()

Define and initialize GPIO pins / Analog I/O pins

Define, start, serial port(s), Ethernet port(s)

4) Loop()

Receive input from ports / GPIO pins / Analog pins

Parse / process data to extract desired information

Use information derived from data to perform desired task (e.g. switch GPIO pins) or to send information to client computer

5) From within Loop(), call other functions() as needed (Optional)

Arduino Example

Include Libraries



Preprocessor directive to include string.h library

Arduino Example Define Variables and Constants

```
8 //define variables
9 String commandInputString = ""; // input buffer string to hold incoming data
10 boolean commandStringComplete = false; // true when the input string is complete
11 String command = ""; // incoming data string for parsing
12
```

Arduino Example Define Variables and Constants

15	//defi	ine o	constant pin aliases
16	const	int	Pin50 = 2; //number of 50 MHz pin
17	const	int	<pre>Pin144 = 3; //number of 144 MHz pin</pre>
18	const	int	<pre>Pin222 = 4; //number of 222 MHz pin</pre>
19	const	int	Pin432 = 5; //number of 432 MHz pin
20	const	int	<pre>Pin902 = 6; //number of 902 MHz pin</pre>
21	const	int	<pre>Pin1296 = 8; //number of 1296 MHz pin</pre>
22	const	int	<pre>Pin2304 = A5; //number of 2304 MHz pir</pre>
23	const	int	<pre>Pin3G = A4; //number of 3GHz pin</pre>
24	const	int	<pre>Pin5G = A3; //number of 5GHz pin</pre>
25	const	int	<pre>Pin10G = A2; //number of 10GHz pin</pre>
26	const	int	<pre>Pin24G = A1; //number of 24GHz pin</pre>
27	const	int	<pre>Pin47G = A0; //number of 47GHz pin</pre>
28	const	int	Pin76G = 7; //number of 76GHz pin

Arduino Example Setup (): Define and Initialize GPIO pins

```
30 void setup() {
                                                      47 //initialize all GPIO pin values to low
31
                                                      48 digitalWrite(Pin50,LOW);
32 // define GPIO pins as output pins
                                                      49 digitalWrite(Pin144,LOW);
33 pinMode(Pin50,OUTPUT);
                                                      50 digitalWrite(Pin222,LOW);
34 pinMode (Pin144, OUTPUT);
                                                      51 digitalWrite(Pin432,LOW);
35 pinMode (Pin222, OUTPUT);
36 pinMode (Pin432, OUTPUT);
                                                      52 digitalWrite (Pin902, LOW);
37 pinMode(Pin902,OUTPUT);
                                                      53 digitalWrite (Pin1296, LOW);
38 pinMode (Pin1296, OUTPUT);
                                                      54 digitalWrite (Pin2304, LOW);
39 pinMode (Pin2304, OUTPUT);
                                                      55 digitalWrite(Pin3G,LOW);
40 pinMode (Pin3G, OUTPUT);
                                                      56 digitalWrite (Pin5G, LOW);
41 pinMode (Pin5G, OUTPUT);
                                                      57 digitalWrite (Pin10G, LOW);
42 pinMode (Pin10G, OUTPUT);
                                                      58 digitalWrite(Pin24G, LOW);
43 pinMode (Pin24G, OUTPUT);
44 pinMode (Pin47G, OUTPUT);
                                                      59 digitalWrite(Pin47G,LOW);
45 pinMode (Pin76G, OUTPUT);
                                                      60 digitalWrite (Pin76G, LOW):
```

- 62 // define, start, flush serial port Serial 0
- 63 // VHF log will send commands to this port
- 64 Serial.begin(9600, SERIAL_8N1); // 9600/8/N/1
- 65 Serial.println("NIMM Bandswitch");
- 66 Serial.println("By W3SZ");
- 67 Serial.println("Uses USB-Serial Port and OTRSP Protocol");
- 68 Serial.println("50 MHz thru 76 GHz");
- 69 delay(100);
- 70

72

```
71 Serial.flush(); // clear buffers
```

Serial class is part of the Arduino Language

•	No need to add library. Members include:	parseInt
	If(Serial)	peek
	available	print
	availableForWrite	println
	begin	read
	end	readBytes
	find	readBytesUntil
	findUntil	setTimeout
	flush	write
	parseFloat	serialEvent

- 62 // define, start, flush serial port Serial 0
- 63 // VHF log will send commands to this port
- 64 Serial.begin(9600, SERIAL_8N1); // 9600/8/N/1

Serial.begin(var1, var2) var1 sets the data rate in bits per second. An optional second argument var2 configures the data, parity, and stop bits. The default is 8 data bits, no parity, one stop bit. Returns nothing.

62 // define, start, flush serial port Serial 0 63 // VHF log will send commands to this port 64 Serial.begin(9600, SERIAL 8N1); // 9600/8/N/1 Serial.println("N1MM Bandswitch"); 65 Serial.println("By W3SZ"); 66 Serial.println("Uses USB-Serial Port and OTRSP Protocol"); 67 Serial.println("50 MHz thru 76 GHz"); 68 69 delay(100); 70Serial.flush(); // clear buffers 71 72

- 62 // define, start, flush serial port Serial 0
- 63 // VHF log will send commands to this port
- 64 Serial.begin(9600, SERIAL_8N1); // 9600/8/N/1
- 65 Serial.println("NIMM Bandswitch");
- 66 Serial.println("By W3SZ");
- 67 Serial.println("Uses USB-Serial Port and OTRSP Protocol");
- 68 Serial.println("50 MHz thru 76 GHz");

Serial.println(data) Prints data to the serial port as human-readable ASCII text followed by a carriage return character (ASCII 13, or '\r') and a newline character (ASCII 10, or '\n'). Returns the number of bytes written.

- 62 // define, start, flush serial port Serial 0
- 63 // VHF log will send commands to this port
- 64 Serial.begin(9600, SERIAL_8N1); // 9600/8/N/1
- 65 Serial.println("N1MM Bandswitch");
- 66 Serial.println("By W3SZ");
- 67 Serial.println("Uses USB-Serial Port and OTRSP Protocol");
- 68 Serial.println("50 MHz thru 76 GHz");
- 69 delay(100);
- 70

72 }

```
71 Serial.flush(); // clear buffers
```

62 // define, start, flush serial port Serial 0 63 // VHF log will send commands to this port

Serial.flush() Waits for the transmission of outgoing serial data to complete. Returns nothing.



- Special built-in function called <u>serialEvent()</u> runs at the end of each Loop() if there is new serial data received
- Lets look at this function before examining Loop() itself

```
333 void serialEvent() {
334
335
     char commandInChar:
336
      while (Serial.available()) { // interrupt generated by hardware serial port
338
        // get the new byte:
339
        commandInChar = (char)Serial.read();
340
341
     // add it to the commandInputString:
342
     commandInputString += commandInChar; // append
343
     // look for a carriage return
344
     // so the main loop can do something about it;
345
      if (commandInChar == '\r') { // the commands all end with a CR
346
           commandStringComplete = true;
347
       1
348
      3
349
```

```
333 void serialEvent() {
334
335 char commandInChar;
336
337 while (Serial.available()) { // interrupt generated by hardware serial port
```

Serial.available() Gets the number of bytes (characters) available for reading from the serial port. This is data that's already arrived and stored in the serial receive buffer (which holds 64 bytes). Returns the number of bytes available to read.

```
333 void serialEvent() {
334
335
     char commandInChar:
336
337
      while (Serial.available()) { // interrupt generated by hardware serial port
338
        // get the new byte:
3
        commandInChar = (char)Serial.read();
340
341
      // add it to the commandInputString:
342
     commandInputString += commandInChar; // append
343
     // look for a carriage return
344
     // so the main loop can do something about it;
345
      if (commandInChar == '\r') { // the commands all end with a CR
346
           commandStringComplete = true;
347
       1
348
      3
349
```

```
333 void serialEvent() {
334
335
      char commandInChar:
336
337
     while (Serial.available()) { // interrupt generated by hardware serial port
338
        // get the new byte:
339
        commandInChar = (char)Serial.read();
Serial.read() Reads incoming serial data. Returns the first byte of incoming
serial data available (or -1 if no data is available)
                       cast (char)
```

```
333 void serialEvent() {
334
335
     char commandInChar:
336
337
     while (Serial.available()) { // interrupt generated by hardware serial port
338
        // get the new byte:
339
        commandInChar = (char)Serial.read();
                                                              commandInputString =
340
                                                              commandInputString +
341
      // add it to the commandInputString:
                                                              commandInChar;
342
     commandInputString += commandInChar; 🖅 append
343
      // look for a carriage return Carriage return is '\r'
344
      // so the main loop can do something about it:
345
      if (commandInChar == '\r') { // the commands all end with a CR
346
          commandStringComplete = true;
347
       1
348
      3
349
```

```
74 void loop() { //MAIN
75
       77
    // get VHFLOG command from serial0
78
   if (commandStringComplete) {
   command = commandInputString;
79
    // save this new command then clear the input buffer
80
81
   // clear the string:
82
   commandInputString = "";
    //set string complete flag to false in preparation for next VHFLOG command;
83
84
    commandStringComplete = false;
85
                                         Serial.print(data)
   //////////// End Command ///////
                                         Prints data to the
  // now process the VHFLOG command
    if (command.length() > 0) {
                                         serial port as human-
88
  readable ASCII text.
90
                                         Returns the number of
     Serial.print("Command is:"
91
     Serial.print(command);
                                         bytes written.
92
```

<pre>95 //set Pin50 high, all other pins low 96 digitalWrite(Pin50,HIGH); 97 digitalWrite(Pin144,LOW);</pre>	
<pre>96 digitalWrite(Pin50,HIGH); 97 digitalWrite(Pin144,LOW);</pre>	
<pre>97 digitalWrite(Pin144,LOW);</pre>	
<pre>98 digitalWrite(Pin222,LOW);</pre>	
<pre>99 digitalWrite(Pin432,LOW);</pre>	
<pre>100 digitalWrite(Pin902,LOW);</pre>	
<pre>101 digitalWrite(Pin1296,LOW);</pre>	
<pre>102 digitalWrite(Pin2304,LOW);</pre>	
<pre>103 digitalWrite(Pin3G,LOW);</pre>	
<pre>104 digitalWrite(Pin5G,LOW);</pre>	
<pre>105 digitalWrite(Pin10G, LOW);</pre>	
<pre>106 digitalWrite(Pin24G, LOW);</pre>	
<pre>107 digitalWrite(Pin47G, LOW);</pre>	
<pre>108 digitalWrite(Pin76G,LOW);</pre>	
<pre>109 Serial.print("Pin50 High");</pre>	
110 }	

Arduino String class

• Members include: charAt compareTo concat c_str endsWith equals equalsIgnoreCase getBytes indexOf lastIndexOf length

remove replace reserve setCharAt startsWith substring toCharArray toInt toFloat toLowerCase toUpperCase trim

94 if ((command.indexOf("AUX100")>=0) || (command.indexOf("AUX200")>=0)) { // set band to 6m

//set Pin50 high, all other pins low

96 digitalWrite (Pin50, HIGH);

- 97 digitalWrite (Pin144, LOW);
- 98 digitalWrite (Pin222, LOW);
- 99 digitalWrite (Pin432, LOW);
- 100 digitalWrite(Pin902,LOW);
- 101 digitalWrite(Pin1296,LOW);
- 102 digitalWrite(Pin2304,LOW);
- 103 digitalWrite(Pin3G,LOW);
- 104 digitalWrite(Pin5G,LOW);
- 105 digitalWrite(PinloG,LOW);
- 106 digitalWrite(Pin24G,LOW);
- 107 digitalWrite(Pin47G,LOW);
- 108 digitalWrite (Pin76G, LOW);

```
109 Serial.print("Pin50 High");
```

```
110
```

95

String.indexOf(val) Locates a character or String val within another String. Returns the index (position) of val within the String, or -1 if val is not found. Position numbering starts with 0.

112	<pre>else if ((command.indexOf("AUX101")>=0) (command.indexOf("AUX201")>=0)) { // set band to 2m</pre>
113	//set Pinl44 high, all other pins low
114	<pre>digitalWrite(Pin50,LOW);</pre>
115	<pre>digitalWrite(Pin144, HIGH);</pre>
116	<pre>digitalWrite(Pin222,LOW);</pre>
117	<pre>digitalWrite(Pin432,LOW);</pre>
118	<pre>digitalWrite(Pin902,LOW);</pre>
119	<pre>digitalWrite(Pin1296,LOW);</pre>
120	<pre>digitalWrite(Pin2304,LOW);</pre>
121	<pre>digitalWrite(Pin3G,LOW);</pre>
122	<pre>digitalWrite(Pin5G,LOW);</pre>
123	<pre>digitalWrite(Pin10G,LOW);</pre>
124	<pre>digitalWrite(Pin24G,LOW);</pre>
125	<pre>digitalWrite(Pin47G,LOW);</pre>
126	<pre>digitalWrite(Pin76G,LOW);</pre>
127	<pre>Serial.print("Pin144 High");</pre>
128	}
129	

130 else if ((command.indexOf("AUX102")>=0) || (command.indexOf("AUX202")>=0)) { // set band to 222 131 //set Pin222 high, all other pins low 132 digitalWrite(Pin50,LOW); 133 digitalWrite (Pin144, LOW); 134 digitalWrite (Pin222, HIGH); 135 digitalWrite (Pin432, LOW); 136 digitalWrite (Pin902, LOW); 137 digitalWrite (Pin1296, LOW); 138 digitalWrite (Pin2304, LOW); 139 digitalWrite (Pin3G, LOW); 140 digitalWrite (Pin5G, LOW); 141 digitalWrite (Pin10G, LOW); 142 digitalWrite (Pin24G, LOW); 143 digitalWrite (Pin47G, LOW); 144 digitalWrite (Pin76G, LOW); 145

300	else if ((command.indexOf("AUX112")>=0) (command.indexOf("AUX212")>=0)) { // set band to 76 GH:
301	//set Pin76G high, all other pins low
302	<pre>digitalWrite(Pin50, LOW);</pre>
303	<pre>digitalWrite(Pinl44,LOW);</pre>
304	<pre>digitalWrite(Pin222,LOW);</pre>
305	<pre>digitalWrite(Pin432,LOW);</pre>
306	<pre>digitalWrite(Pin902,LOW);</pre>
307	<pre>digitalWrite(Pin1296,LOW);</pre>
308	<pre>digitalWrite(Pin2304,LOW);</pre>
309	<pre>digitalWrite(Pin3G,LOW);</pre>
310	<pre>digitalWrite(Pin5G,LOW);</pre>
311	<pre>digitalWrite(PinlOG, LOW);</pre>
312	<pre>digitalWrite(Pin24G,LOW);</pre>
313	<pre>digitalWrite(Pin47G,LOW);</pre>
314	<pre>digitalWrite(Pin76G, HIGH);</pre>
315	}
316	// cleanup
317	<pre>command = ""; // clear the VHFLOG command</pre>
318	}
319	//////////////////////////////////////
320	
321	
322	<pre>delay(25); // long enough for the radio to return its frequency</pre>
323	
324	} //END MAIN

Programming Steps

- 1) Included libraries containing classes with external functions
- 2) Defined variables and constants
- 3) Setup ()
 - Defined and initialized GPIO pins
 - Defined, started serial port
- 4) Loop()
 - Received input from serial port
 - Parsed / processed data to extract desired information
 - Used information derived from data to perform desired task (switch GPIO pins)
- 5) Called serialEvent() at end of every loop cycle

Questions?

